Chapter 3 Arrays

Matrices

Example

(Tabular Display of Data) The following matrix gives the airline distance; between the indicated cities (in miles):

	London	Madrid	NewYork	Tokyo
London	0	785	3469	5959
Madrid	785	0	3593	6706
New York	3469	3593	0	6757
Tokyo	5959	6706	6757	0

The windchill table that follows is a matrix .A combination of air temperature and wind speed makes a body feel cooler than the actual temperature.For example when temperature is 10 °F and the wind is 15 miles per hour ,this causes body heat loss equal to that when the temperature is -18 °F with no wind.

	°F	°F	°F	°F	°F	°F
	15	10	5	0	-5	-10
mph						
5	12	7	0	-5	-10	-15
10	-3	-9	-15	-22	-27	-34
15	-11	-18	-25	-31	-38	-45
20	-17	-24	-31	-39	-46	-53

Two Dimensional Arrays:

Matrices

A matrix has multiple rows and columns

Example: The matrix M

$$\mathbf{M} = \begin{bmatrix} 2 & 4 & 10 \\ 16 & 3 & 7 \\ 8 & 4 & 9 \\ 3 & 12 & 15 \end{bmatrix}$$

has four rows and three columns.

Creating Matrices

If the matrix is small you can type it row by row, separating the *elements* in a given row with *spaces* or *commas* and separating the *rows* with semicolons. For example, typing

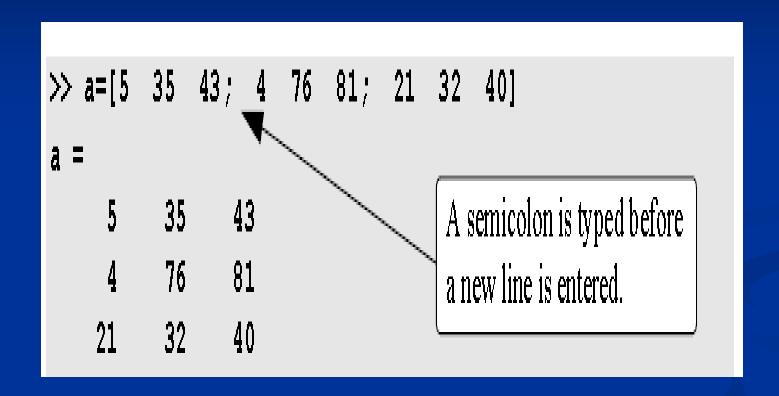
Example

$$>>$$
A = [2,4,10;16,3,7];

creates the following matrix:

$$A = \begin{bmatrix} 2 & 4 & 10 \\ 16 & 3 & 7 \end{bmatrix}$$

Remember, spaces or commas separate elements in different *columns*, whereas semicolons separate elements in different *rows*.



Creating Matrices from Vectors

Suppose

```
a = [1, 3, 5]
And
b = [7, 9, 11]
```

Note the difference between the results given by

[a b]

[a;b]

in the following session:

```
>>c = [a b];
c =
1 3 5 7 9 11
>>D = [a;b]
D =
1 3 5
7 9 11
```

You need not use symbols to create a new array. For example, you can type

```
>> D = [[1,3,5];[7,9,11]];
```

Matrices and transpose Operation

- Transpose operation interchanges rows and columns. Transpose operation is carried out by '
- \sim >> A=[-2 6;-3 5]
- $\blacksquare A =$
- -2 6
- -3 5
- <u>>> A'</u>
- □ ans =
- **□** -2 -3

Array Addressing

- A(:,3) denotes all the elements in the third column of the matrix A.
- A(:,2:5) denotes all the elements in the second through fifth columns of A.
- A(2:3,1:3) denotes all the elements in the second and third rows that are also in the first through third columns.
- v = A(:) creates a vector v consisting of all the columns of A stacked from first to last.
- A(end,:) denotes the last row in A, and A(:,end) denotes the last column.

>> A=[1 3 5 7 9 11; 2 4 6 8 10 12; 3 6 9 12 15 18; 4 8 12 16 20 24; 5 10 15 20 25 30]

Define a matrix A with 5 rows and 6 columns.

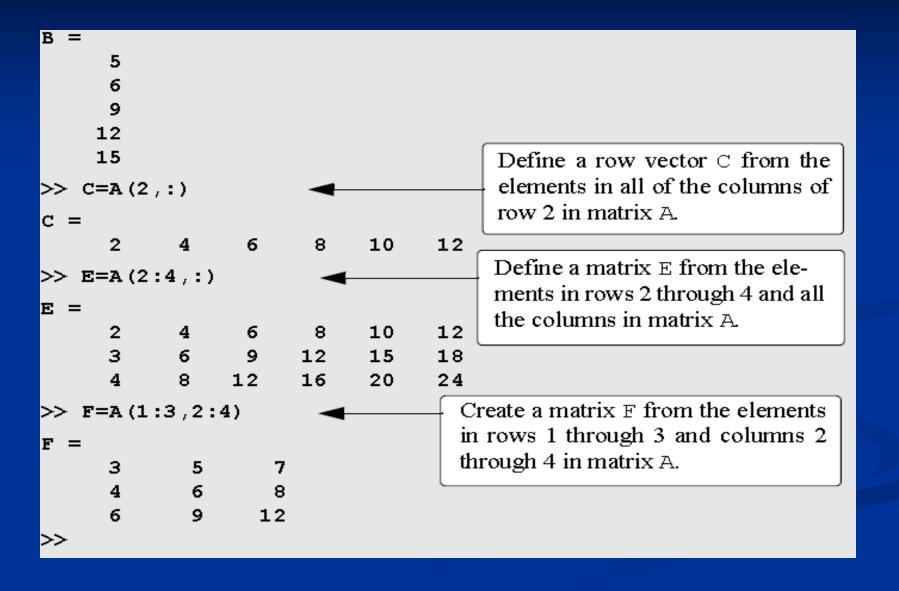
A =

1	3	5	7	9	11
2	4	6	8	10	12
3	6	9	12	15	18
4	8	12	16	20	24
5	10	15	20	25	30

 \gg B=A(:,3)

Define a column vector B from the elements in all of the rows of column 3 in matrix A.

Continued from example



```
>> MAT=[3 11 6 5; 4 7 10 2; 13 9 0 8]
                                              Create a 3 \times 4 matrix.
MAT =
         11
       7 10 2
    13
                               Assign a new value to the (3,1) element.
>> MAT (3,1)=20
MAT
         11
                   10
    20
                             Use elements in a mathematical expression.
>> MAT (2,4)-MAT (1,2)
ans =
    -9
```

You can use array indices to extract a smaller array from another array. For example, if you first create the array **B**

$$\mathbf{B} = \begin{bmatrix} 2 & 4 & 10 & 13 \\ 16 & 3 & 7 & 18 \\ 8 & 4 & 9 & 25 \\ 3 & 12 & 15 & 17 \end{bmatrix}$$

then type C = B(2:3,1:3), you can produce the following array:

$$\mathbf{C} = \begin{bmatrix} 16 & 3 & 7 \\ 8 & 4 & 9 \end{bmatrix}$$

Additional Array Functions

and v, containing the row and column indices of the nonzero elements of the matrix A, and the array w, containing the values of the nonzero elements. The array w may be omitted.

length(A) Computes the largest value of m or n if A is an $m \times n$ matrix.

continued

max (A) Returns a row vector containing the largest elements in each column if A is a matrix.

If any of the elements are complex, max (A) returns the elements that have the largest magnitudes.

continued

[x,k] = max(A) Similar to max(A) but
stores the maximum values in the row
vector x and their indices in the row vector
k.

min(A) Same as max(A) but returns
the minumum values

[x, k] = min(A) same as [x,k]=max(A) but returns the minumum values

continued

size(A)

sort(A)

sum(A)

Returns a row vector [m n] containing the sizes of the m x n array A.

Sorts each column of the array A in ascending order and returns an array the same size as A.

Sums the elements in each column of the array A and returns a row vector containing the sums.

```
>> A=[6 2;-10 -5;3 0]
A =
  6 2
 -10 -5
  3
      0
>> max(A)
ans =
  6
     2
>> min(A)
ans =
 -10 -5
>> size(A)
ans =
  3
      2
```

```
>> length(A)
ans =
  3
>> sort(A)
ans =
 -10 -5
 3 0
    2
>> sum(A)
ans =
  -1 -3
```

For example, if

$$\mathbf{A} = \begin{bmatrix} 6 & 0 & 3 \\ 0 & 4 & 0 \\ 2 & 7 & 0 \end{bmatrix}$$

then the session

$$>>A = [6, 0, 3; 0, 4, 0; 2, 7, 0];$$

 $>>[u, v, w] = nd(A)$

returns the vectors

$$\mathbf{u} = \begin{bmatrix} 1\\3\\2\\3\\1 \end{bmatrix} \qquad \mathbf{v} = \begin{bmatrix} 1\\1\\2\\2\\3 \end{bmatrix} \qquad \mathbf{w} = \begin{bmatrix} 6\\2\\4\\7\\3 \end{bmatrix}$$

The vectors \mathbf{u} and \mathbf{v} give the (row, column) indices of the nonzero values, which are listed in \mathbf{w} . For example, the second entries in \mathbf{u} and \mathbf{v} give the indices (3, 1), which speci es the element in row 3, column 1 of \mathbf{A} , whose value is 2.

- The complete syntax of the sort function is sort(A, dim, mode), where dim selects a dimension along which to sort and mode selects the direction of the sort, 'ascend' for ascending order and 'descend' for descending order.
- The min, max ,sort function can be made to act on rows instead of columns by transposing the array

So, for example, sort(A,2, 'descend') would sort the elements in each row of **A** in descending order $>> A=[6\ 0\ 3;0\ 4\ 0;2\ 7\ 0]$

Element by Element Operations

Multiplying a matrix by a scalar w produces a matrix whose elemnts are the elements of A multiplied by w

>>
$$A = [-2.6; -3.5]$$
 $A =$
 -2.6
 -3.5
>> $5*A$
ans =
 -10.30

-15 25

Array Addition and Subtraction

For example:

$$\begin{bmatrix} 6 & -2 \\ 10 & 3 \end{bmatrix} + \begin{bmatrix} 9 & 8 \\ -12 & 14 \end{bmatrix} = \begin{bmatrix} 15 & 6 \\ -2 & 17 \end{bmatrix}$$

Array subtraction is performed in a similar way.

The addition shown above is performed in MATLAB as follows:

```
>>A = [6,-2;10,3];

>>B = [9,8;-12,14]

>>A+B

ans =

15 6

-2 17
```

Element by Element Multiplication:

Element by Element division

```
>> C=A./B
C =
-1.5714 0.6250
-1.5000 2.0000
```

Element by Element Exponentiation

$$A =$$

MATRIX OPERATIONS

Vector Matrix Multiplication

```
>> A=[27;6-5]
A =
  2 7
   6
    -5
>> b=[3;9]
b =
  3
   9
>> A*b
ans =
  69
 -27
```

Matrix-Matrix Multiplication

In the product of two matrices **AB**, the number of columns in **A** must equal the number of rows in **B**.

The product **AB** has the same number of *rows* as **A** and the same number of *columns* as **B**.

Use the operator * to perform matrix multiplication in MATLAB. The following MATLAB session shows how to perform the matrix multiplication shown in.

Example

```
>> A=[6 -2;10 3;4 7]
A =
   6
      -2
  10 3
   4
>> B=[9 8;-5 12]
B =
      8
      12
```

```
>> A*B
```

ans =

64 2475 1161 116

Matrix multiplication does not have the commutative property; that is, in general, $AB \neq BA$. A simple example will demonstrate this fact:

$$\mathbf{AB} = \begin{bmatrix} 6 & -2 \\ 10 & 3 \end{bmatrix} \begin{bmatrix} 9 & 8 \\ -12 & 14 \end{bmatrix} = \begin{bmatrix} 78 & 20 \\ 54 & 122 \end{bmatrix}$$

whereas

$$\mathbf{BA} = \begin{bmatrix} 9 & 8 \\ -12 & 14 \end{bmatrix} \begin{bmatrix} 6 & -2 \\ 10 & 3 \end{bmatrix} = \begin{bmatrix} 134 & 6 \\ 68 & 66 \end{bmatrix}$$

Reversing the order of matrix multiplication is a common and easily made mistake.

The following product is de ned in matrix multiplication and gives the result shown:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \begin{bmatrix} y_1 & y_2 & y_3 \end{bmatrix} = \begin{bmatrix} x_1y_1 & x_1y_2 & x_1y_3 \\ x_2y_1 & x_2y_2 & x_2y_3 \\ x_3y_1 & x_3y_2 & x_3y_3 \end{bmatrix}$$

The following product is also de ned:

Example

Matrix multiplication of a column vector x and a row vector y produces a matrix

```
>> x=[3;4;7]
X =
   3
   4
>> y=[578]
   5
           8
>> X*y
ans =
  15
       21
            24
       28
            32
  20
  35
       49
            56
```

Product of a row vector x by a matrix A pruduces a row vector Example

Height versus Velocity

The maximum height h achieved by an object thrown with a speed ν at an angle θ to the horizontal, neglecting drag, is

$$h = \frac{v^2 \sin^2 \theta}{2g}$$

Create a table showing the maximum height for the following values of ν and θ :

$$v = 10, 12, 14, 16, 18, 20 \text{ m/s}$$
 $\theta = 50^{\circ}, 60^{\circ}, 70^{\circ}, 80^{\circ}$

The rows in the table should correspond to the speed values, and the columns should correspond to the angles.

```
>> clear
```

- >> % g acceleration of gravity
- >> g=9.81;
- >> % v is the speed
- >> V=[10:2:20];
- >> % theta is the angle
- >> theta=[50:10:80];

 $>> h=((v'.^2)*(sind(theta).^2))/(2*g)$

h =

```
2.9909
                           4.9432
         3.8226
                  4.5006
4.3070
         5.5046
                  6.4809
                           7.1181
                  8.8212
5.8623
         7.4924
                           9.6886
7.6568
         9.7859
                  11.5216
                           12.6545
                  14.5820
9.6907
         12.3853
                            16.0158
11.9638
         15.2905
                   18.0025
                            19.7726
```

>> % T is the table

>> T=[0 theta; v' h]

$$T =$$

```
50.0000 60.0000
                        70.0000
                                  80.0000
10.0000
         2.9909
                  3.8226
                           4.5006
                                    4.9432
12.0000
         4.3070
                  5.5046
                           6.4809 7.1181
14.0000
                  7.4924
                           8.8212
                                    9.6886
         5.8623
16.0000
                  9.7859
         7.6568
                           11.5216
                                    12.6545
18.0000
         9.6907
                  12.3853
                           14.5820
                                    16.0158
20.0000
                            18.0025
         11.9638
                  15.2905
                                     19.7726
```

Special Matrices

Two exceptions to the noncommutative property are the *null* or *zero* matrix, denoted by **0** and the *identity*, or *unity*, matrix, denoted by **I**.

The null matrix contains all zeros and is not the same as the *empty* matrix [], which has no elements.

These matrices have the following properties:

$$0A = A0 = 0$$

$$IA = AI = A$$

The identity matrix is a square matrix whose diagonal elements are all equal to one, with the remaining elements equal to zero.

For example, the 2×2 identity matrix is

$$\mathbf{I} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

The functions eye (n) and eye (size (A)) create an $n \times n$ identity matrix and an identity matrix the same size as the matrix A.

Example

```
>> idn=eye(5)
idn =

1 0 0 0 0
0 0 0
0 1 0 0 0
0 0 1 0 0
0 0 0 1 0
0 0 0 1 0
```

Sometimes we want to initialize a matrix to have all zero elements. The zeros command creates a matrix of all zeros.

Typing zeros (n) creates an $n \times n$ matrix of zeros, whereas typing zeros (m, n) creates an $m \times n$ matrix of zeros.

Typing zeros (size (A)) creates a matrix of all zeros having the same dimension as the matrix **A**. This type of matrix can be useful for applications in which we do not know the required dimension ahead of time.

The syntax of the ones command is the same, except that it creates arrays filled with ones.

Matrix Left Division and Linear Algebraic Equations

```
6x + 12y + 4z = 70
7x - 2y + 3z = 5
2x + 8y - 9z = 64
>>A = [6,12,4;7,-2,3;2,8,-9];
>>b = [70;5;64];
>>Solution = A\b
Solution =
   3
   -2
The solution is x = 3, y = 5, and z = -2.
```

Inverse of a Matrix

The matrix B is the inverse of the matrix A if, when the two matrices are multiplied, the product is the identity matrix. Both matrices must be square and the multiplication order can be BA or AB.

$$BA = AB = I$$

$$>> A=[2 1 4;4 1 8;2 -1 3]$$

$$A =$$

- 2 1 4
- 4 1 8
- 2 -1 3

continued

```
>> B=inv(A)
B =
5.5000 -3.5000 2.0000
2.0000 -1.0000 0
-3.0000 2.0000 -1.0000
```

1 0 0 0 1 0 0 0 1